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that is concerned predominantly with mechanics has a brief section devoted to computational considerations. This book evolved from class notes used to teach "Introduction to Robotics" at Stanford University during the autunms of 1983 through 1985. The first and second editions have been used at many institutions from 1986 through 2002. The third

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Now in its second edition, Introduction to Robotics is intended for senior and introductory graduate courses in robotics. Designed to meet the needs

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